

Lezione #3

11/03/2025

CINEMATICA

$$\vec{v}; \Delta \vec{v}; \vec{v}_M = \frac{\Delta \vec{v}}{\Delta t} \rightarrow \vec{v}_{IST} = \frac{d\vec{v}}{dt}$$

accelerazione:

$$\vec{a}_M = \frac{\Delta \vec{v}}{\Delta t}$$

$$[\vec{a}_M] = \frac{[v]}{[t]} = \frac{m}{s} \frac{1}{s} = m/s^2$$

$$\vec{a}_{IST} = \lim_{\Delta t \rightarrow 0} \frac{\Delta \vec{v}}{\Delta t} = \frac{d\vec{v}}{dt}$$

se $\vec{a}_M = \frac{\Delta \vec{v}}{\Delta t}$ $a_M = \text{COSTANTE}$ se e solo se

\vec{a} $\left\{ \begin{array}{l} \text{Modulo} \\ \text{Direz.} \\ \text{Verso} \end{array} \right.$

MOTO UNIF. ACCELERATO IN DUE DIMENSIONI



$$\vec{a} = \text{COSTANTE} \quad \vec{a}_{IST} = \vec{a}_M = \vec{a}$$

$$\begin{cases} t_{IN} = 0 \\ t_{FIN} = t \end{cases} \quad \begin{cases} \vec{r}_{IN} = \vec{r}_0 \\ \vec{r}_{FIN} = \vec{r} \end{cases} \quad \begin{cases} \vec{v}_{IN} = \vec{v}_0 \\ \vec{v}_{FIN} = \vec{v} \end{cases} \quad a_{IN} = a_{FIN} = a$$

$$\vec{a} = \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v} - \vec{v}_0}{t - 0}$$

$$\vec{v} = \vec{v}_0 + \vec{a} t$$

$$\begin{cases} v_x = v_{0x} + a_x t \\ v_y = v_{0y} + a_y t \end{cases}$$

$$\vec{v} = (v_x; v_y)$$

$$\vec{v}_M = \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v} - \vec{v}_0}{t - 0}$$

$$\vec{r} = \vec{r}_0 + \vec{v}_M t \leftarrow$$

$$\left(\vec{v}_M = \frac{\vec{v}_0 + \vec{v}}{2} \right) \quad \text{Valore medio}$$

$$\vec{r} = \vec{r}_0 + \underbrace{\left(\frac{\vec{v}_0 + \vec{v}}{2} \right)}_{\vec{v}_M} t$$

$$\vec{r} = \vec{r}_0 + \frac{1}{2} \vec{v}_0 t + \frac{1}{2} \vec{v} t \quad \downarrow (\vec{v}_0 + \vec{a} t)$$

$$= \vec{r}_0 + \frac{1}{2} \vec{v}_0 t + \frac{1}{2} \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$$

$$\underbrace{\frac{1}{2} \vec{v}_0 t + \frac{1}{2} \vec{v}_0 t}_{\frac{1}{2} (\vec{v}_0 + \vec{a} t) t} + \frac{1}{2} \vec{a} t^2$$

$$\vec{r} = \vec{r}_0 + \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$$

$$\frac{1}{2} (\vec{v}_0 + \vec{a} t) t$$

$$\left\{ \begin{array}{l} x = x_0 + v_{0x} t + \frac{1}{2} a_x t^2 \\ y = y_0 + v_{0y} t + \frac{1}{2} a_y t^2 \end{array} \right.$$

$\vec{a} = g \hat{j}$ MOTO UNIF. ACC. IN \Rightarrow VE \Rightarrow M.

$$\vec{r} = \vec{r}_0 + \vec{v}_0 t + \frac{1}{2} \vec{a} t^2$$

$$\left\{ \begin{array}{l} x = x_0 + v_{0x} t + \frac{1}{2} a_x t^2 \\ y = y_0 + v_{0y} t + \frac{1}{2} a_y t^2 \end{array} \right.$$

$$\vec{v} = \vec{v}_0 + \vec{a} t$$

$$\left\{ \begin{array}{l} v_x = v_{0x} + a_x t \\ v_y = v_{0y} + a_y t \end{array} \right.$$

Quando $\vec{a} = \vec{g}$

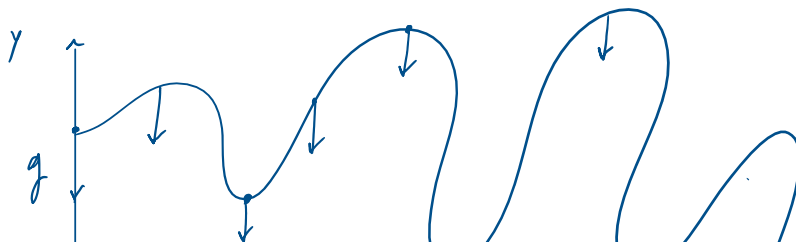
\hookrightarrow accelerazione di gravità



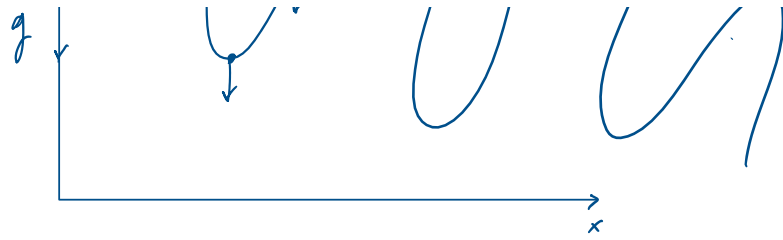
Moto in caduta libera in due dimensioni

$$g = 9,81 \text{ m/s}^2$$

$$\vec{a} = (0; -g)$$

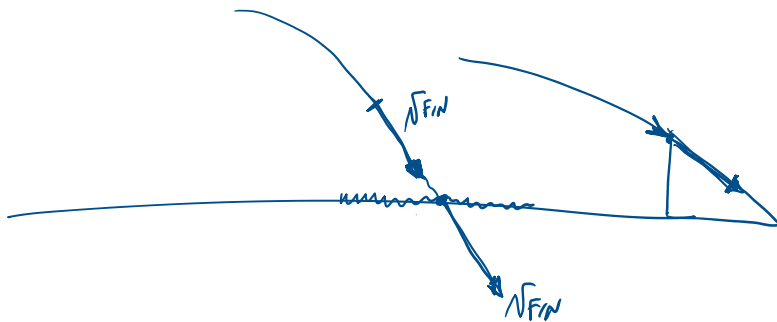
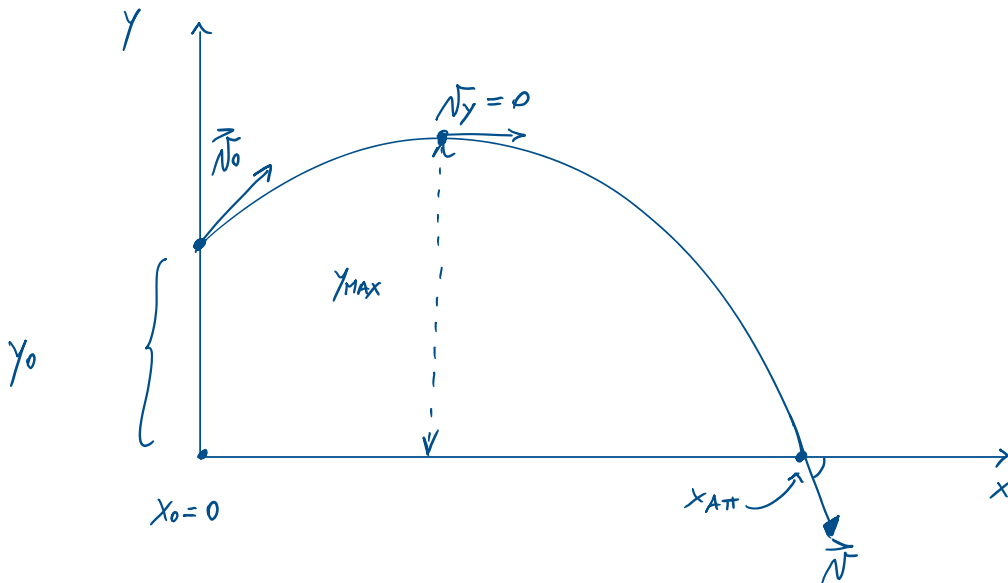


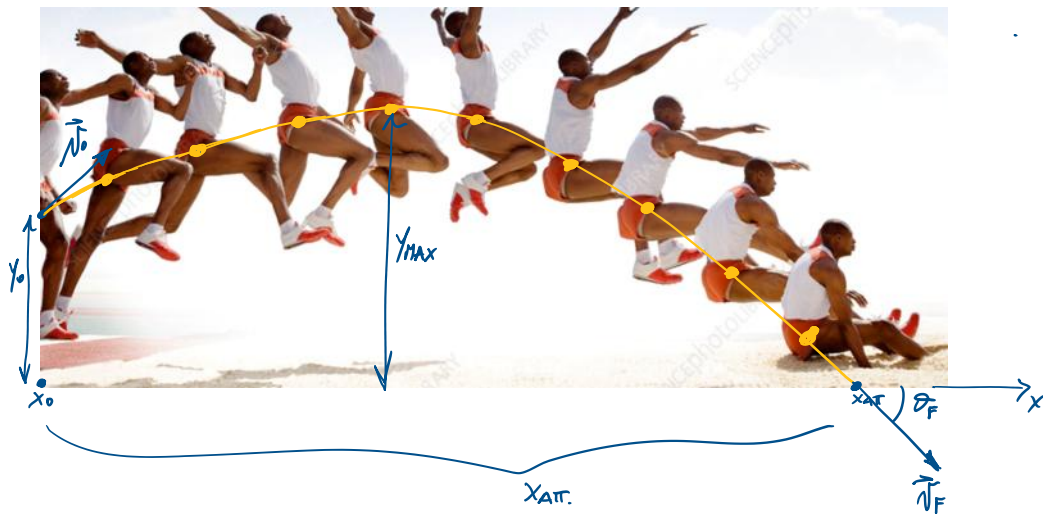
$$\vec{a} = (0; -g)$$



$$\begin{cases} x = x_0 + v_{0x}t + \frac{a_x t^2}{2} = x_0 + v_{0x}t \Leftarrow \text{N. cost.} \\ y = y_0 + v_{0y}t + \frac{1}{2} a_y t^2 = y_0 + v_{0y}t - \frac{1}{2} g t^2 \Leftarrow \text{acc. } < 0 \end{cases}$$

$$\begin{cases} v_x = v_{0x} + a_x t = v_{0x} \\ v_y = v_{0y} + a_y t = v_{0y} - g t \end{cases}$$





Moto in caduta libera \Rightarrow x moto rettilineo uniforme ($v_x = \text{cost.}$)

$$\begin{cases} v_x = v_{0x} \\ x = x_0 + v_{0x} t \end{cases}$$

Esempio moto in caduta libera:

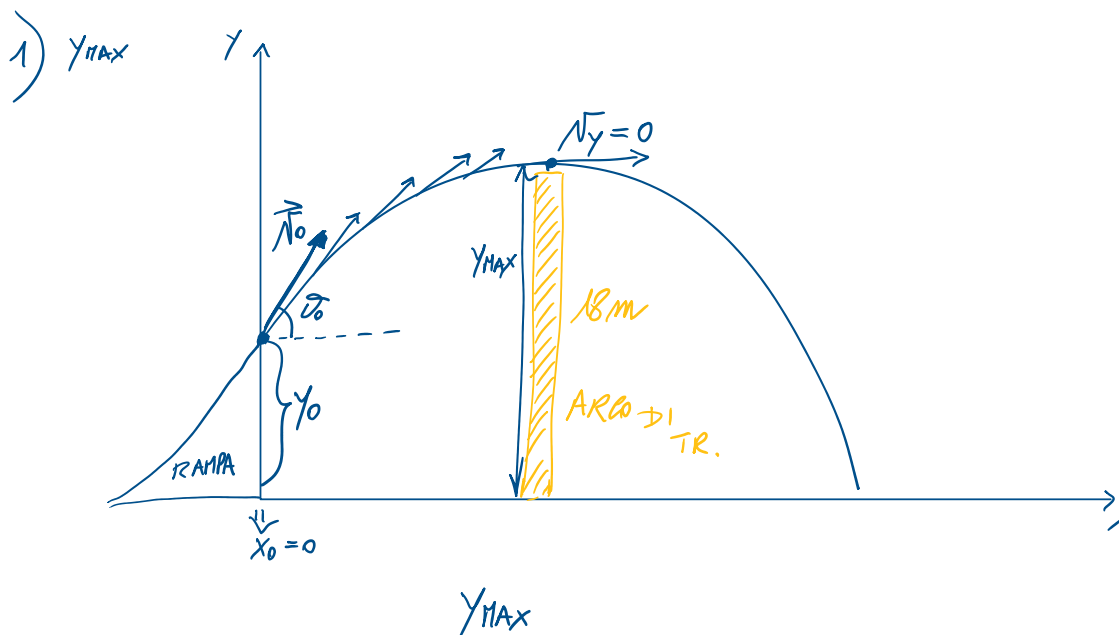
Esercizio:



A capodanno 2007 lo stuntman Robbie Madison tentò di stabilire un nuovo record a Las Vegas cercando di superare una replica dell'Arco Di Trionfo alta 18 m. Sapendo che si lanciò con una velocità iniziale pari a $v_0 = 90 \text{ km/h}$ da una rampa alta $y_0 = 3 \text{ m}$ e inclinata con un angolo $\theta = 45^\circ$, calcolare:

1. Altezza massima raggiunta. Riesce a superare l'Arco?
2. La distanza di atterraggio
3. Il modulo, direzione e verso della sua velocità finale (all'atterraggio)

(Lo stesso Madison nell'impatto col terreno, si lacerò la mano tra pollice e indice e dichiarò che non avrebbe mai ripetuto tale impresa neppure per 10 milioni di dollari)



Per calcolare $y_{\text{MAX}} \Rightarrow v_y = 0$

$$v_y = v_{0y} - g t$$

$$0 = v_{0y} - g t_{\text{MAX}}$$

$$g t_{\max} = v_{0y}$$

$$t_{\max} = v_{0y}/g$$

1° Poss. t_{\max} calcolo simultaneo

$$v_{0y} = v_0 \sin \theta_0$$



$$t_{\max} = \frac{v_0 \sin \theta_0}{g}$$

$$v_0 = 90 \text{ km/h} = 90 \frac{10^3 \text{ m}}{60 \cdot 60 \text{ min}} = 90 \frac{10^3}{36 \cdot 10^3} \frac{\text{m}}{\text{s}}$$

$$v_0 = 25 \text{ m/s}$$

$$t_{\max} = \frac{25 \cdot \sin(45^\circ)}{9,81} = 1,80200 \text{ s}$$

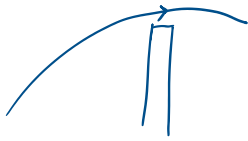
Sostituisco t_{\max} in y

$$y_{\max} = y_0 + v_{0y} t_{\max} - \frac{1}{2} g t_{\max}^2$$

$$= 3 + 25 \cdot \sin(45^\circ) \cdot 1,80200 - \frac{1}{2} \cdot 9,81 \cdot (1,80200)^2$$

$$y_{\max} = 18,92 \text{ m} > 18 \text{ m} \quad \downarrow$$





2^a STRADA

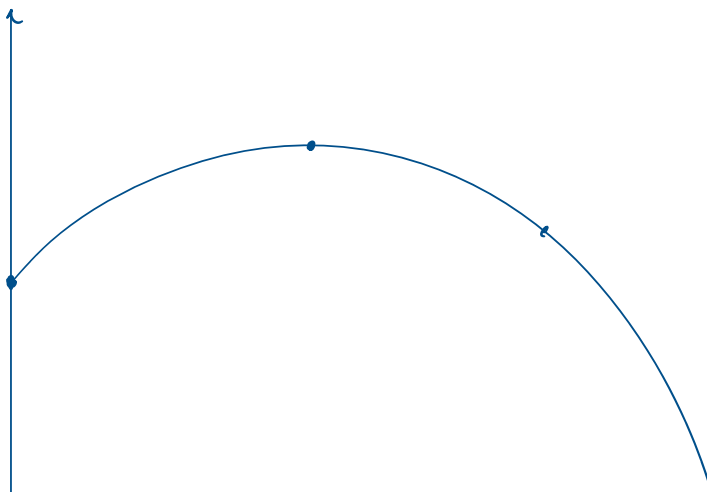
$$t_{\max} = \frac{v_0 \sin \theta_0}{g} \quad \Rightarrow \quad y = y_0 + v_{0y} \left(\frac{v_{0y}}{g} \right) - \frac{1}{2} g \left(\frac{v_{0y}}{g} \right)^2$$

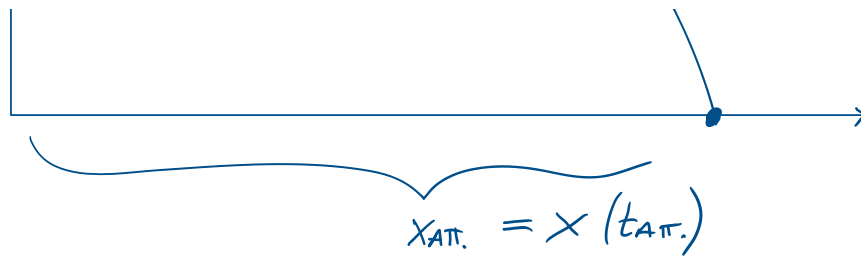
$$\downarrow \\ = y_0 + \frac{1}{2} \frac{v_{0y}^2}{g} - \frac{1}{2} g \frac{v_{0y}^2}{g^2} = y_0 + \frac{1}{2} \frac{v_{0y}^2}{g}$$

$$y_{\max} = y_0 + \frac{1}{2} \frac{v_{0y}^2}{g} = y_0 + \frac{1}{2} \frac{(v_0 \sin \theta_0)^2}{g}$$

$$y_{\max} = 18,92 \text{ m} \approx 20 \text{ m (l.c.s.)}$$

2) x_{AT} ?





$$X_{ATT.} \Rightarrow y = 0$$

Se imponiamo $y = 0$
 \Downarrow

$$y = y_0 + v_{0y}t - \frac{1}{2}gt^2$$

$$y = 0 \Rightarrow 0 = y_0 + v_{0y}t - \frac{1}{2}gt^2$$

\hookrightarrow risolvere rispetto a t

$$t^2 \underbrace{\left(-\frac{1}{2}g\right)}_a + t \underbrace{\left(v_{0y}\right)}_b + \underbrace{y_0}_c = 0$$

$$a = -4,9050$$

$$b = 17,677$$

$$c = 3$$

Formula risolutiva

$$t_{1,2} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$$

$$\left. \begin{array}{l} 3,7664 \text{ s} \\ -0,1629 \text{ s} \end{array} \right\}$$

$$L = 0,1664 \text{ s}$$

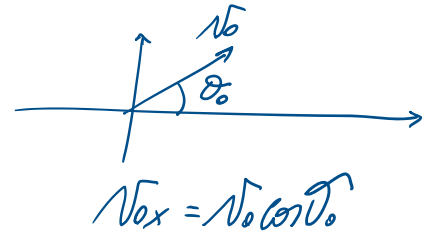


$$t_{ATP} = 3,7664 \text{ s}$$

$$x = x_0 + v_{0x} t$$

$$x_{ATP} = v_{0x} t_{ATP}$$

$$x_{ATP} = v_0 \cos \theta_0 t_{ATP}$$



$$x_{ATP} = 25 \cdot \cos(45^\circ) \cdot 3,7664 =$$

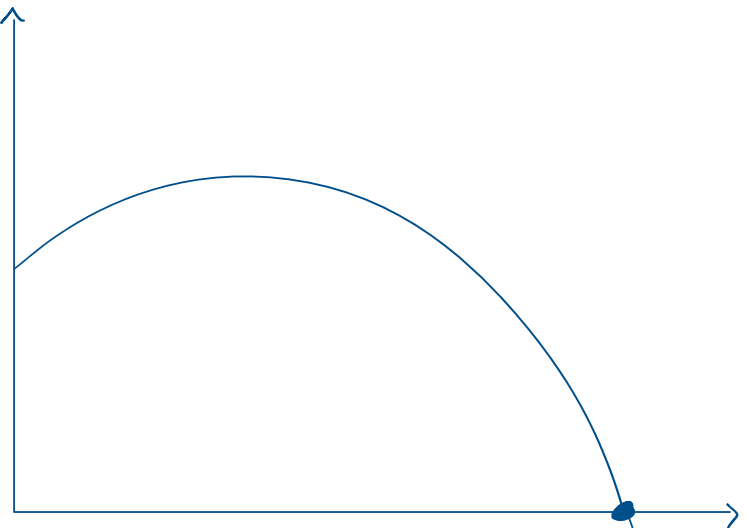
$$x_{ATP} = 66,5811 \text{ m} \approx 70 \text{ m (1 c.s.)}$$

3) \vec{v}_F ?



Corrisponde $t = t_{ATP}$

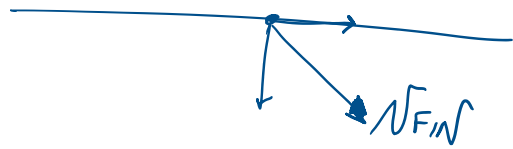
$$t_{ATP} = 3,7664 \text{ s}$$



$$\begin{cases} v_x = v_{0x} = v_0 \cos \theta_0 = 25 \cos(45^\circ) \\ v_y = v_{0y} - g t_{ATP} = v_0 \sin \theta_0 - g t_{ATP} = \end{cases}$$

$$\begin{aligned}
 | v_y &= v_{0y} - g t_{\text{att.}} = v_0 \sin \theta_0 - g t_{\text{att.}} = \\
 &= 25 \sin(45^\circ) - 9,81 \cdot 3,7664
 \end{aligned}$$

$$\begin{cases}
 v_x = 17,6777 \text{ m/s} \\
 v_y = -19,2707 \text{ m/s}
 \end{cases}$$



$$v_F = \sqrt{v_x^2 + v_y^2} = 26,1505 \text{ m/s}$$

$$\boxed{v_F \approx 30 \text{ m/s (u.s.)}}$$