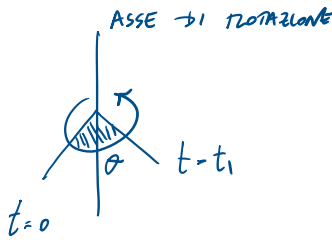


Lezione #8 30/3/2022

$$\vec{F} = M_{TOT} \vec{a}_{CM}$$

$$\vec{M} = \vec{r} \times \vec{F}$$

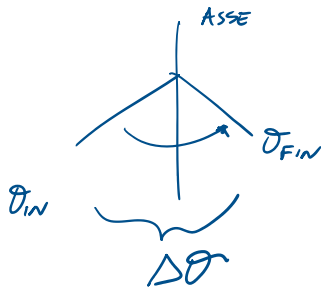
Velocità angolare:



θ PERCORSO IN UN INT. DI TEMPO

$$\omega = \frac{\Delta\theta}{\Delta t} = \frac{\theta_F - \theta_W}{\Delta t}$$

Omega; velocità angolare



$$[\omega] = \frac{\text{rad}}{\text{s}}$$

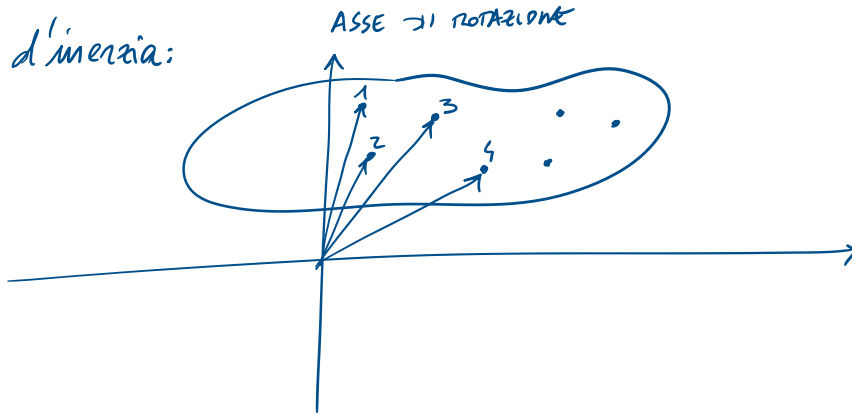
Accelerazione angolare

$$\alpha = \frac{\Delta\omega}{\Delta t}$$

$$[\alpha] = \text{rad/s}^2$$

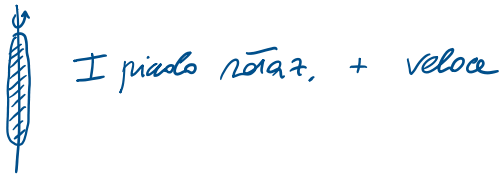
alfa

Momento d'inerzia:



$$I = m_1 r_1^2 + m_2 r_2^2 + \dots + m_n r_n^2$$

↳ momento di inerzia
(misura di dispersione masse rispetto all'asse di rotazione)



$$\begin{cases} \vec{F} = M_{TOT} \vec{a}_{COM} & I \text{ egre cardinale (TRASLAE.)} \\ \vec{M} = I \vec{\alpha} & \text{II " " (ROTAE.)} \end{cases}$$

$$\vec{F} \leftrightarrow \vec{M}$$

$$\vec{M}_{TOT} \leftrightarrow \vec{I}$$

$$\vec{a}_{\text{cor}} \leftrightarrow \vec{\alpha}$$

In generale :

$$\left\{ \begin{array}{l} \vec{F} = \frac{d}{dt} (m \vec{v}_{\text{cor}}) = m \vec{a}_{\text{cor}} \quad \left(\begin{array}{l} \text{SIST.} \\ \text{A MASSA FISSA} \end{array} \right) \\ \vec{M} = \frac{d}{dt} (I \vec{\omega}) = I \vec{\alpha} \quad \left(\begin{array}{l} \text{quando} \\ I \text{ \u00e9 cost.} \end{array} \right) \end{array} \right.$$

LE CONDIZIONI DI EQUILIBRIO SONO

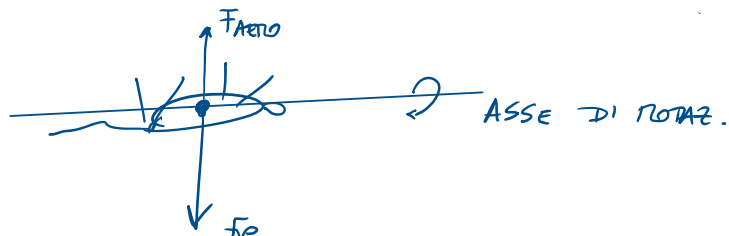
$$\left\{ \begin{array}{l} \vec{F} = \vec{0} \\ \vec{M} = \vec{0} \end{array} \right.$$

Ma quando $\vec{M} = \vec{0} \Rightarrow \frac{d}{dt} (I \vec{\omega}) = 0$

$$\Rightarrow \boxed{I \omega = \text{cost.}}$$

APPLICAZIONE RIFLESSO VERTICALE DEL GATTO:

Due forze in gioco: $\vec{F}_p + \vec{F}_{\text{FRENO}} = \vec{F}^{\text{RIS}}$





Rispetto all'asse di rotazione
 sia τ_p che F_{FRENO} hanno momento
 nullo ($\vec{r} = \vec{0}$)

$$M = 0 \Rightarrow I\omega = \text{cost.}$$

Il gatto "divide" il corpo a metà
 prima rammicchia il corpo intorno alle
 zampe anteriori $\Rightarrow I \downarrow \Rightarrow \omega \uparrow$
 " " sono + ruotate rispetto alle
 posteriori (1) + (2)

3) Allunga le zampe anteriori che
 rallentano $\omega \downarrow$

l'opposto con le zampe posteriori

4) 5) Per rallentare la caduta

$$\text{spinta } F_{\text{FRENO}} = \frac{1}{r} \int_{\uparrow}^{\downarrow} A C v^2$$

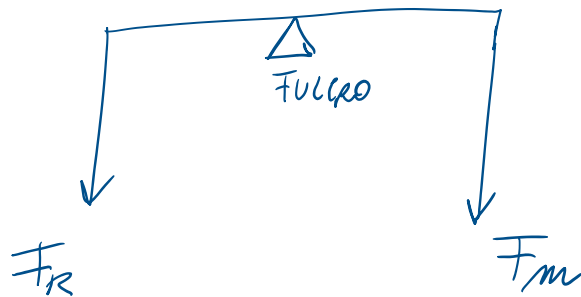
sfurto $F_{AERO} = \frac{1}{2} \rho A c v^2$

↑ ↑

Paracadute $A \nearrow \quad c \nearrow$

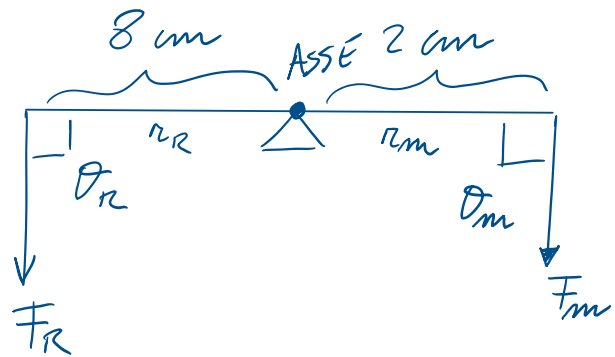
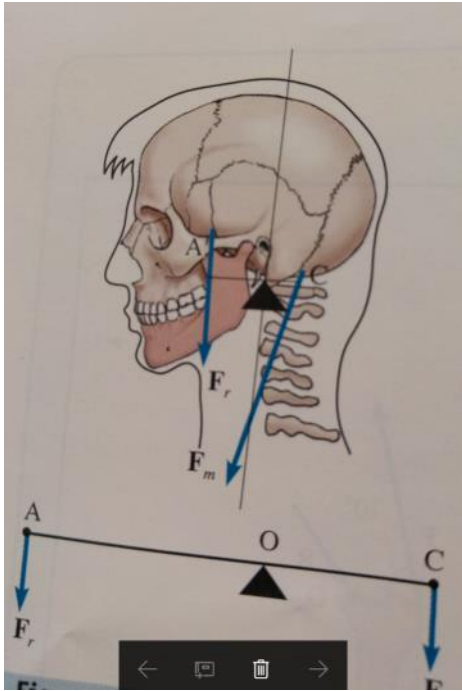
LEVE

LEVA I° TIPO



Tutte le leve si basano sull'equilibrio del sistema fisico considerato:

$$\left\{ \begin{array}{l} \vec{F}^{(RIS)} = \vec{0} \\ \vec{M}^{(RIS)} = \vec{0} \end{array} \right.$$



$$\theta_r = \theta_m = 90^\circ$$

$$F_r = 80 \text{ N}$$

$$r_r = 8 \text{ cm}$$

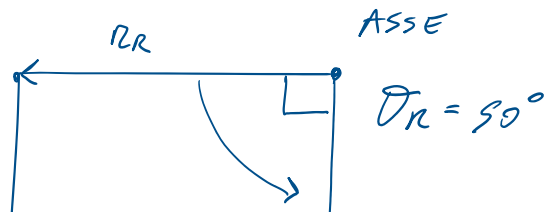
$$r_m = 2 \text{ cm}$$

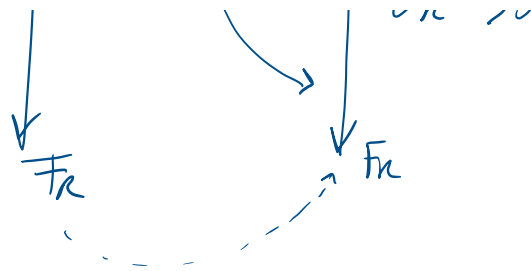
All'equilibrio:

$$\vec{M}^{\text{ris}} = \vec{0} = \vec{M}_r + \vec{M}_m = \vec{0}$$

Calcolare quanto $F_m = ?$

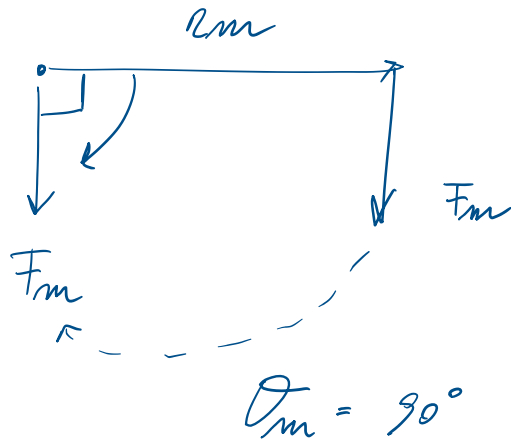
\vec{M}_r :





$$M_R = r_R F_R \quad \checkmark$$

\vec{M}_m :



$$M_m = - r_m F_m$$

$\theta_m = 90^\circ$

$$M^{ris} = \begin{matrix} r_R F_R & - & r_m F_m & = & 0 \\ \uparrow & \uparrow & \uparrow & \downarrow & ? \end{matrix}$$

$$F_m = \frac{r_R}{r_m} F_R$$

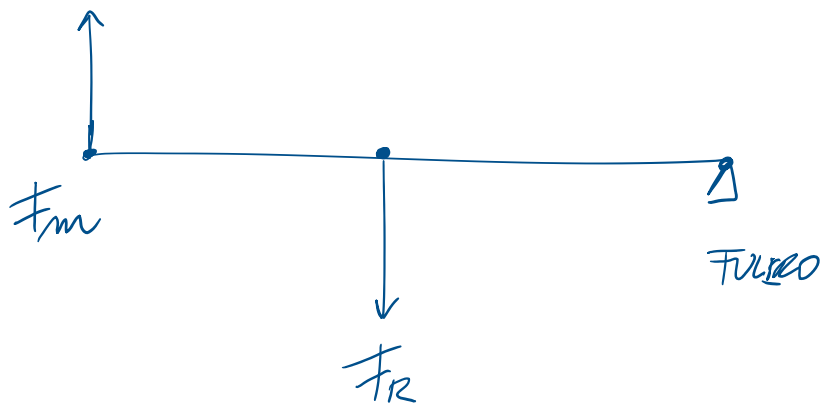
$$F_m = \frac{0,08}{0,02} F_R$$

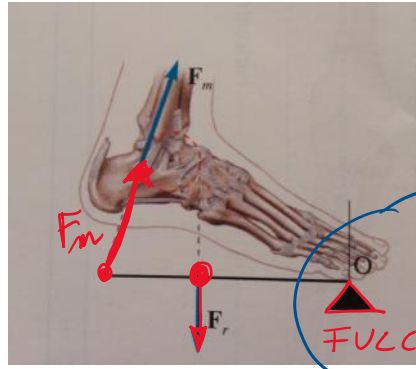
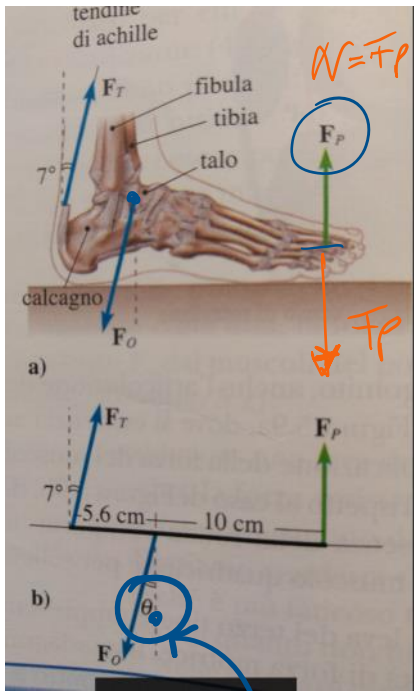
$$F_m = 4 F_r$$

I muscoli splenici esercitano una forza motrice pari a 4 volte la F_r del cranio!!!

$$F_m = 4 \cdot 80 = 320 \text{ N} \quad \checkmark$$

LEVA II TIPO:





F_T : Tensione nel Tendine di Achille

$\theta = 7^\circ$

F_o : F. esercitata dalle ossa (Tibia e Fibula)

F_p : F. peso (reazione del suolo)

θ_o ?

$r_T = 5,6 \text{ cm} = 0,056 \text{ m}$

$r_P = 10 \text{ cm} = 0,1 \text{ m}$

$\theta_T = 7^\circ$

$\theta_P = 90^\circ$

F_P : considerata nota

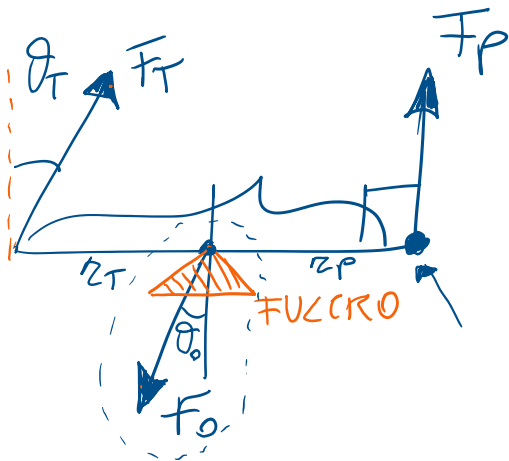
$r_P = 0,1 \text{ m}$

$r_T = 0,056 \text{ m}$

$\theta_T = 7^\circ$

F_T ? come f^{me} di F_P

F_o ; θ_o incognite



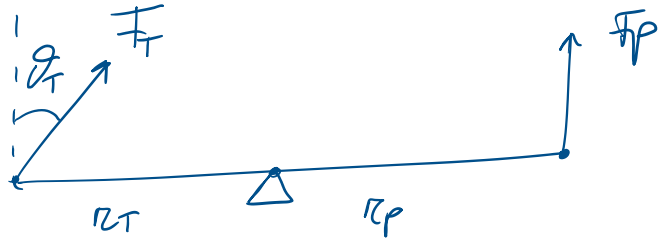
Se scelgo l'asse di azione al

azione su

$F_0; \sigma_0$ integrale

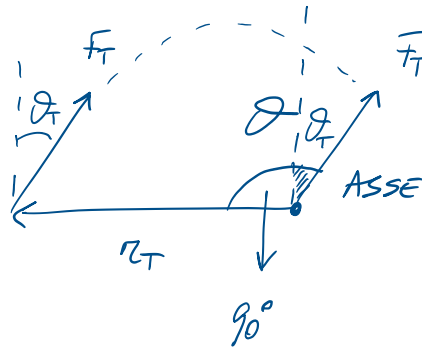
$$\vec{M}^{(RIS)} = \vec{0}$$

$$\vec{M}_T + \vec{M}_{F_P} + \cancel{\vec{M}_0} = 0$$



$$F_T = ?$$

M_T

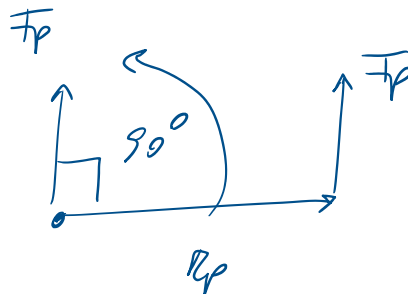


$$\vartheta = 90^\circ + \alpha_T = (\pi/2 + \alpha_T)$$

$$M_T = - r_T F_T \sin(\pi/2 + \alpha_T)$$



M_P



$$M_P = + r_P F_P$$

$$M^{(Ris)} = - r_T F_T \sin\left(\frac{\pi}{2} + \theta_T\right) + r_P F_P = 0$$

(90° + 4°)

$$F_T = \frac{r_P}{r_T} \frac{F_P}{\sin\left(\frac{\pi}{2} + \theta_T\right)}$$

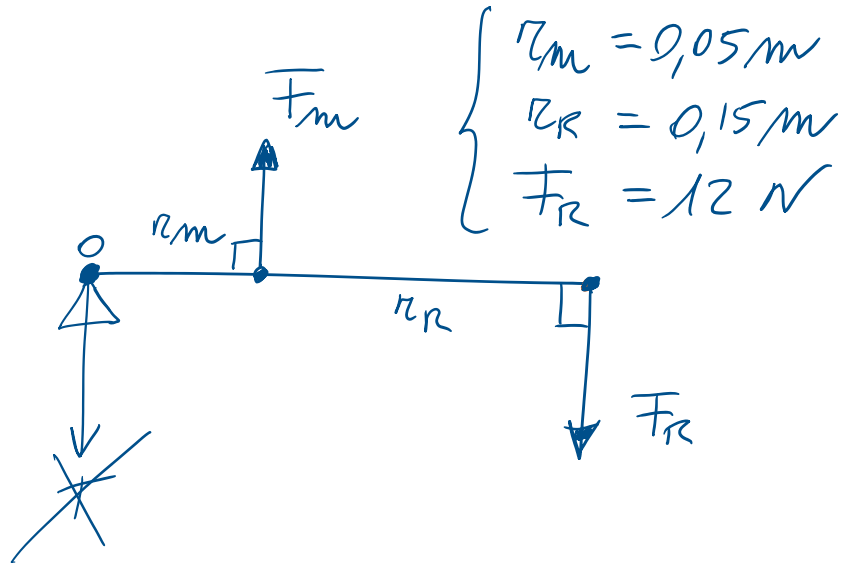
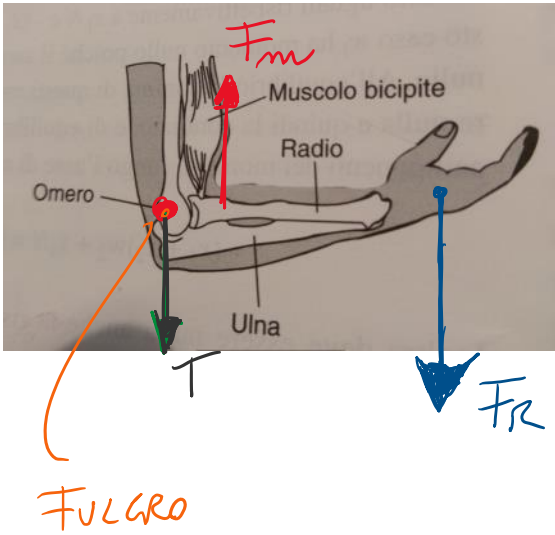
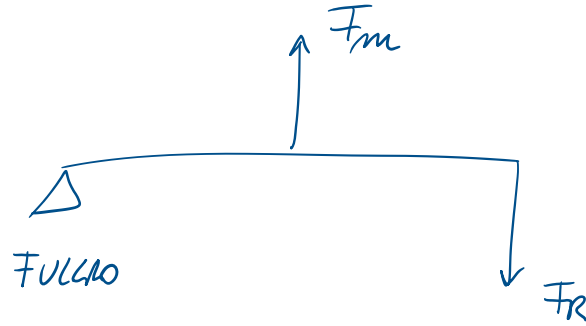
$$F_T = \frac{0,1}{(0,56 \cdot 0,9975)} F_P$$

$$F_T \approx 1,8 F_P$$

Per ogni singolo passo la tensione nel tendine d'Achille è pari al doppio delle F_P !!!

LEVA III TIRÒ

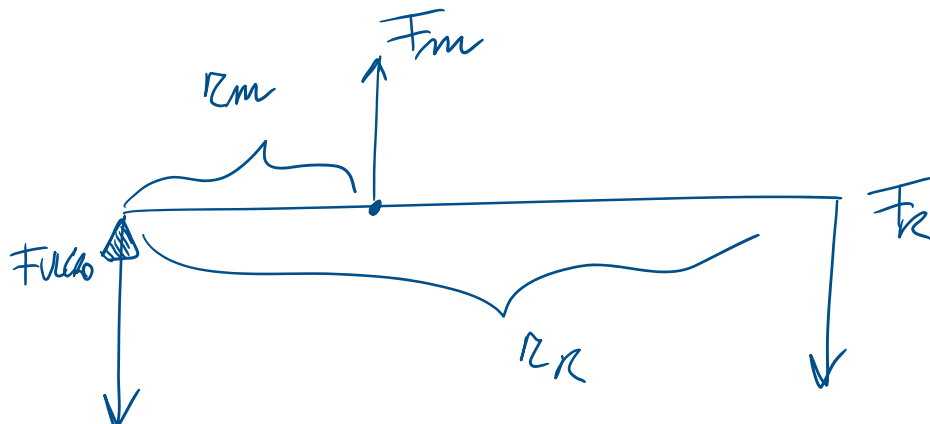
T



F_m ? sforzo nei bicipiti
 T ? tensione \rightarrow omero

$$\sum \vec{F}^{(e)} = \vec{0}$$

$$\sum \vec{M}^{(e)} = 0$$



$$\sum \bar{M}^{(k)} = \vec{0}$$

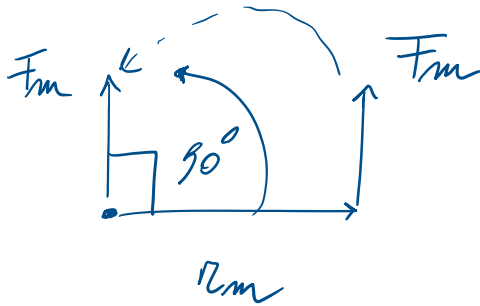


r_r



$$\vec{M} = \vec{0} \quad \vec{M}_m + \vec{M}_r = \vec{0}$$

M_m :

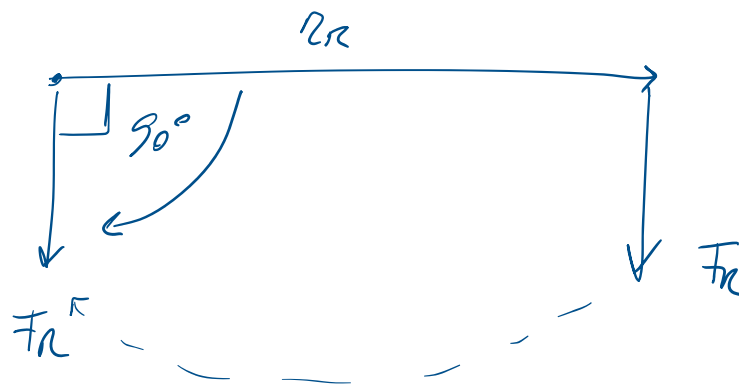


sens antiorario

$$M_m > 0$$

$$M_m = r_m F_m$$

M_r :



sens

orario

$$M_r < 0$$

$$M_r = - r_r F_r$$

$$M^{ris} = r_m F_m - r_r F_r = 0$$

$$F_m = \frac{r_r}{r_m} F_r$$

$$F_m = 3 F_r$$

Sen licquite si esecute una forza nomi al
Triplo del peso alzere ✓